Industry Response to Pesticide Regulators' "State of the Knowledge" Review of Unmanned Aerial Vehicle (UAV) Use for Pesticide Application

Overview of the Unmanned Aerial Pesticide Application System Task Force (UAPASTF)

Sarah Hovinga Regulatory Scientific Affairs, Regulatory Policy Analyst, Digital Farming Bayer Crop Science

IUPAC ICCPC, New Delhi, India March 17th, 2023



Global regulatory landscape of drone application technology

North America

USA: EPA defers to states provided aerial application is allowed on the federal label.

CAN: Some registered labels for drones, overall policy being developed.

Latin America

BRA, CRI, URY: Drone application is allowed once aerial application is already approved on the label.

GTL, COL, MEX: Some drone application permitted. Regulation under discussion.

ECU, PER: Drone application not allowed. Regulation under discussion.

Europe, Middle East, Africa

EU: Mostly aerial application banned except with specific exemptions.

DEU, CHE Drone application allowed for specific applications.

HUN: local regulation under construction.

Burkina Faso, Ghana, Kenya, Zambia, South Africa: strong interest in drone application Asia Pacific

JPN, KOR: Most advanced countries. Application via drones allowed, regulations in place.

MYS, PHL, IND: Regulations in place.

CHN, THA, IDN, VNM: Commercial use permitted/permitted soon while guidance is developed in parallel

PAK,MMR: Regulations under development

OECD WPP Drone/UASS Subgroup

Founded in August 2019 by the Working Party on Pesticides (WPP) to provide guidance on regulation Organisation for Economic Cooperation and Development (OECD) of use of unmanned aerial vehicles for application of crop protection products

> Principles for a regulatory framework for UAV application





OECD WPP Drone/UASS Subgroup

OECD Drone/UAV Subgroup of WPP

Overview of Participants

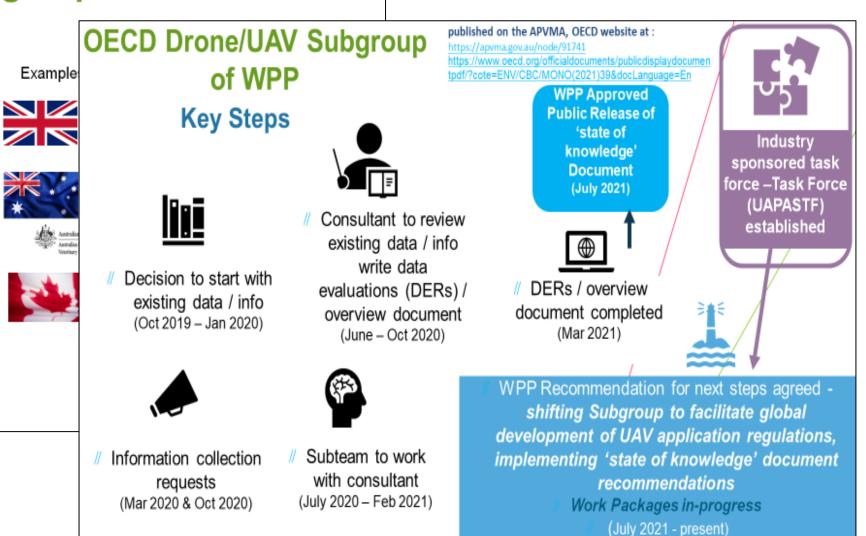
BETTER POLICIES FOR BETTER LIVES

A global effort

- # OECD member countries, led by the United Kingdom
- **# European Commission**

// Business at OECD (BIAC)

// Invited Experts



4

OECD WPP Drone/UASS Subgroup

			Grouping of Recommendations from 'State of Knowledge' Report
Work Package #1 – off-		<u>Work Package #1</u> – off-	#7. Develop an empirical database and standard drift curve or model to estimate off
	\$	site exposure including	target exposure.
		exposure modeling	#9. Develop a useable publicly available model for predicting spray deposition and
	L	(BIAC / CDN / US)	drift including parameters for static hovering, forward speed and spray equipment.
//	The Subgroup ha	S	#1. Establish database to classify UASS into groups to reduce burden of testing each
11	become an	Work Package #2 –	different platform/configuration.
	advisory body to		#2. Survey manufacturers about future trend of UASS design/ use profiles to produce
	provide expert	stakeholders (UK)	a benchmark platform as a common starting point for regulators (others may differ and need bespoke assessment but would cover most common uses).
	input on how to f knowledge gaps		#8. A data gathering exercise for operational practices mixing, loading, cleaning and transport scenarios.
	// Grouping of 'state)	#5. Develop and publish a user-friendly summary of best practice (including the
	of knowledge' recommendations	Work Package #3 –	essential nature of calibration), pitfalls and a trouble shooting guide (both for
	needed to develop		generating trials data and applying pesticides in practice), including preliminary
	implement	guidance (BIAC)	recommendations for operational parameters (release height, application volumes, forward speed and spray quality).
	// Workstreams		
	Established, work in-progress		#6. Promote the advice in Annex D recommendations for researchers conducting UASS drift studies.
	p. eg. eee	Work Package #5 –	#4. Develop set of standard methodologies that will support regulatory decision making.
		connect to ISO	#3. Encourage manufacturers to develop improved spray systems including the
		(Research Institute / ISO	pump systems, nozzle placement and closed transfer loading systems. * ISO
	5	representative)	standard project



- Where appropriate, the UAPASTF will focus on <u>generating data</u> for submission to <u>pesticide</u> <u>regulatory authorities</u> to inform estimates for <u>off-site</u> <u>movement</u>, determine potential <u>operator/handler</u> <u>exposure</u>, and assess <u>crop residue</u> contribution to human dietary exposure in risk assessment and regulatory approval processes.
- // UAPASTF alignment with work of the OECD WPP Drone/UASS Subgroup critical to success
- // UAV-based pesticide application a part of progression toward precision / digital agriculture with the potential for increasing sustainability



Industry sponsored task force (UAPASTF) established



- **#** Based in the US but **global** in its work / focus
- // UAPASTF to interact with OECD Drone/UASS Subgroup of WPP, regional / national regulators, CropLife, & other stakeholders to develop & provide information / data
- **// UAPASTF Definitive Agreement Approved, Leadership Selected**

UAPASTF Member Company	Administrative Committee Representative	Technical Committee Representative
BASF Corporation	David Haughey	Frank Donaldson (Chair)
Bayer CropScience LP	Greg Watson (Chair)	Jane Tang
Corteva Agriscience	Travis Bui (Vice Chair)	Rajeev Sinha
FMC Corporation	Hector Portillo	Roberto Barbosa
NuFarm Americas Inc.	Patti Turner	Tyler Gullen
Syngenta Crop Protection LLC	Becca Haynie (Treasurer)	Shanique Grant (Vice Chair)
Valent U.S.A. LLC	Robin Charlton	Banugopan Kesavaraju

- // Task force managers: Rhonda Bichsel & Eric Bruce
- # Established collaborative agreements with UAV-application companies, seeking further agreements with other companies (e.g., additional UAV-application companies in other world areas, UAV & nozzle manufacturers)



Parties interested in the work of, or registrants interested in joining the UAPASTF should contact: Dr. Greg Watson, Chair, UAPASTF Administrative Committee greg.watson@bayer.com +1 314 343 8120



Industry sponsored task force – (UAPASTF) established

- // Technical teams actively working
 - // Off-site movement GLP study protocol & trials (Dave Haughey and Frank Donaldson, BASF)
 - // Including identifying 'reference' / 'benchmark' UAV & spray system
 - // Development of an off-site exposure estimate/model for UAV-based pesticide application related to environmental/ecological risk assessment
 - " 'Best practices' guidance (Hector Portillo, FMC)
 - // Field crop residue project Canada (Pam Livingston, Syngenta)

CLA Interim Drift Key Takeaways

- Initial indications support the assumption that from a spray drift perspective, UASS curves are somewhere between aerial and ground-based methodologies, comparing closest to orchard airblast applications, based on the published literature.
 - Comparisons were done to basic drift curves for the EU, US, and Canada (See Figures 6 & 7 for examples)

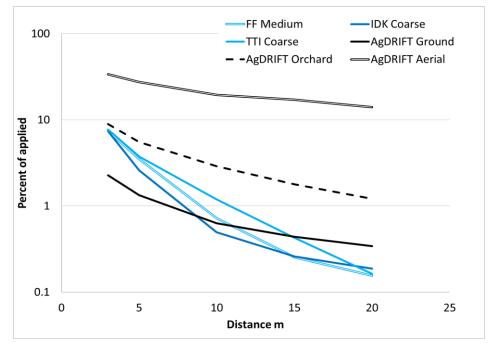
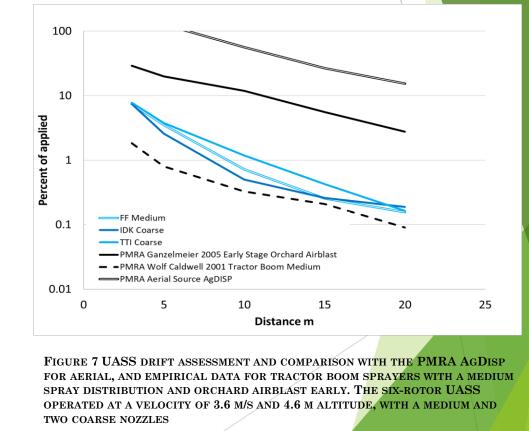


FIGURE 6 UASS DRIFT ASSESSMENT AND COMPARISON WITH THE EPA AGDRIFT 2.1.1 ORCHARD, GROUND, AND AERIAL CURVES. THE SIX-ROTOR UASS OPERATED AT A VELOCITY OF 3.6 M/S AND 4.6 M ALTITUDE, WITH A MEDIUM AND TWO COARSE NOZZLES



Bonds, J., Pai, N., Hovinga, S., Haynie, B., Bui, T., Flack, and Stump, K. Uncrewed aerial spray systems and equivalency with conventional techniques: spray drift, operator exposure, crop residue, and efficacy [Conference Presentation]. ACS Fall 2022, Chicago, IL, United States. <u>https://acs.digitellinc.com/acs/session</u> 512038/view





ndustry sponsored task force – task force (UAPASTF) established

Technical teams actively working

- // Advancing work of Crop Life America project with Dr. J. Bonds, development of interim exposure estimate/model based on empirical data
 - // Determine quality criteria for data to include in further exposure estimate/model work,
 - // Request additional raw data from published off-site movement studies,
 - // Incorporation of UAPASTF off-site movement study protocol data into these exposure estimates, &
 - // Mathematical approach to use raw data to develop off-site movement curves
- // Longer term: development of a mechanistic off-site exposure estimate/model for UAV-based pesticide application
 - // <u>Desired</u>: establishment of a tripartite (e.g., government / academia / industry) forum for development of exposure estimates for regulatory purposes

OECD Drone/UASS Subgroup of WPP <u>Work Package #1</u> – offsite exposure including exposure modeling (BIAC / CDN / US)



- // Technical teams actively working
 - // Off-site movement GLP study protocol, 8-10 GLP field studies planned in 2023
 - // Including identifying 'reference' / 'benchmark' UAV & spray system
 - // Potential trial sites in North America, Latin America, Europe, Africa, & Australia being considered
 - // Non-GLP 'dry runs' 1^{st} Q 2023
 - // Focus in 2023 will be in North America, Latin America, Europe. Other regions included in 2024.
 - // Input from internationally recognized off-site movement experts sought & received
 - // Requested review / input from OECD WPP Drone / UASS Subgroup on study protocol

OECD Drone/UASS Subgroup of WPP <u>Work Package #1</u> – offsite exposure including exposure modeling (BIAC / CDN / US)

Industry sponsored task force – (UAPASTF) established

ation (

Industry sponsored task force –

> (UAPASTF) established

- // Technical teams actively working
- // 'Best Practices' guidance
 - // Preparation of draft completed by UAPASTF 4th Q 2022
 - // Shared with UAPASTF collaborators 4th Q 2022
 - // Targeting 1st Q 2023 for external stakeholder input on draft
 - // OECD Cooperative Research Program funded workshop in 2023 for additional expert / stakeholder input on this guidance
 - // In-person, May 23rd & 24th 2023, York, UK
 - // Expressions of interest requested by Feb 28th, https://www.hsl.gov.uk/health-and-safety-training-courses/crdconference-and-workshop-applying-pesticides-using-drones
- // Field Crop residue project Canada

12

// Supporting efforts for a funded Agriculture and AgriFood Canada project to address PMRA questions OECD Drone/UASS Subgroup of WPP <u>Work Package #3 –</u> 'best practices' guidance (BIAC)

- // UAPASTF global core mission is to supply regulatory data / information to inform the potential use of UAVbased pesticide application
- // UAPASTF alignment with work of the OECD WPP Drone/UASS Subgroup critical to success
- // UAV-based pesticide application a part of progression toward precision / digital agriculture with the potential for increasing sustainability



Thank you! Please reach out with any questions:

Sarah.Hovinga@bayer.com

Acknowledgements to the members below and others involved in the UAPASTF work

UAPASTF Member Company	Administrative Committee Representative	Technical Committee Representative
BASF Corporation	David Haughey	Frank Donaldson (Chair)
Bayer CropScience LP	Greg Watson (Chair)	Jane Tang
Corteva Agriscience	Travis Bui (Vice Chair)	Rajeev Sinha
FMC Corporation	Hector Portillo	Roberto Barbosa
NuFarm Americas Inc.	Patti Turner	Tyler Gullen
Syngenta Crop Protection LLC	Becca Haynie (Treasurer)	Shanique Grant (Vice Chair)
Valent U.S.A. LLC	Robin Charlton	Banugopan Kesavaraju