Industry (UAPASTF) Response to Pesticide Regulators "State of the Knowledge" Review of Unmanned Aerial Vehicle (UAV) Use for Pesticide Application: Developing Best Practices for Safe and Effective Application of Pesticides Using Unmanned Aerial Spray Systems (UASS)



Industry sponsored task force – task force (UAPASTF) established

Hector Portillo, Ph.D.

Senior Global R&D Product Manager, FMC Corporation

Best Practices Guidance Document Lead | BIAC representative at OECD DRONE/UAV subgroup | UAPASTF Administrative Committee Member, FMC UAPASTF: Unmanned Aerial Pesticide Application System Task Force

Acknowledgement: Greg Watson and UAPASTF Best Management Practices Technical Team

# **Factor Driving Adoption of UAVs for Pesticide Application**



Socioeconomical Factors



Technology Factors

- Ageing and decreasing farming population.
- Migration to cities.
- Rising labor cost.
- Safety to applicator/farmer, reduced exposure.
- More efficient and accurate application method compared to some alternatives such as backpack.
- Fits small size farms and difficult terrain (hills, paddies, wet fields).
- Remote sensing and variable rate spraying.
- Improvements and lower cost in the fields of electronics, optics, computer science, GPS, energy storage and others.

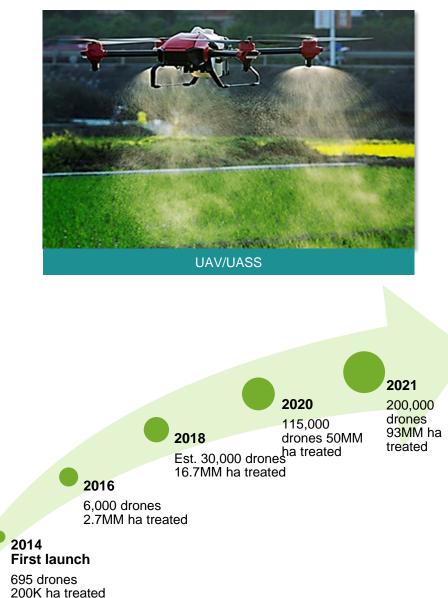
### **UAVs Have Replaced Mostly High Exposure and Less Accurate Application Methods in China**



Gas Powered Pump-Large Hose



Hand Pump Back-Pack



Oil Palm Bagworm Example in Malaysia: UAVs Becoming A New Method of Application That Provides Better Coverage and Less Exposure

**Conventional Methods of Application Used** 



Airblast



Backpack



Airplane application possible, but too expensive



**Trunk Injection** 

### New tool being introduced, Commercial experiences needed



### UAVs Can Complement Other Application Methods: i.e., Spot Applications, Borders, Sensitive Areas

1. UAV Complementing Ground Application on Trees



2. UAV Complementing airplane Sprays Near Power Lines







# **UAV Applications Outside Asia - Switzerland**

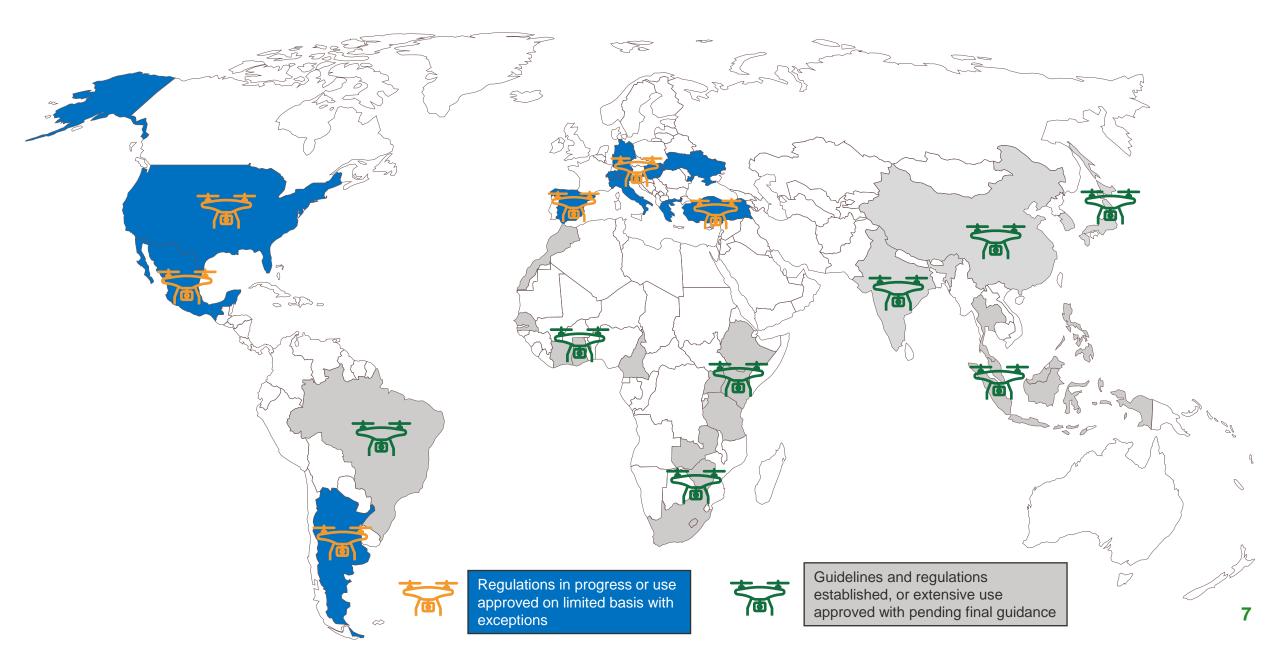


Switzerland among few EU countries that have aerial application approved, use of helicopters for spraying in difficult to reach vineyards grown in steep hills.

Transition from there to UASS by conducting their own studies to show the uniformity of spray with UASS in vineyard, guideline ISO 16122-2 issued



Countries In Process or with Regulatory Approvals for use of UAV/UASS for Pesticide Applications



## OECD WPP Drone/UASS Subgroup - Previous Presentation

			Grouping of Recommendations from 'State of Knowledge' Report
		/ork Package #1 – off-	#7. Develop an empirical database and standard drift curve or model to estimate off
b b e	si	te exposure including	target exposure.
		exposure modeling	#9. Develop a useable publicly available model for predicting spray deposition and
	The Subgroup has become an advisory body to provide expert input on how to fill knowledge gaps	(BIAC / CDN / US)	drift including parameters for static hovering, forward speed and spray equipment.
		Work Package #2 –	#1. Establish database to classify UASS into groups to reduce burden of testing each different platform/configuration.
		scanning / survey to	#2. Survey manufacturers about future trend of UASS design/ use profiles to produce a benchmark platform as a common starting point for regulators (others may differ and need bespoke assessment but would cover most common uses).
			#8. A data gathering exercise for operational practices mixing, loading, cleaning and transport scenarios.
	<ul> <li>Grouping of state of knowledge' recommendations needed to develop / implement</li> <li>Workstreams</li> </ul>	windige       Work Package #3 –       essential nature of calibration), pitfalls and a trouble         eeded to develop /       'best practices'       generating trials data and applying pesticides in pract         oplement       guidance (BIAC)       forward speed and spray gualit	#5. Develop and publish a user-friendly summary of best practice (including the essential nature of calibration), pitfalls and a trouble shooting guide (both for generating trials data and applying pesticides in practice), including preliminary recommendations for operational parameters (release height, application volumes, forward speed and spray quality).
	Established, work in- progress		#6. Promote the advice in Annex D recommendations for researchers conducting UASS drift studies.
	P. 09.000	Work Package #5 – making.	#4. Develop set of standard methodologies that will support regulatory decision making.
		<b>connect to ISO</b> (Research Institute / ISO	#3. Encourage manufacturers to develop improved spray systems including the pump systems, nozzle placement and closed transfer loading systems. * ISO standard project
	8	representative)	

### Work Package 3 Update (Best Practices)



Unmanned Aerial Spray

Systems (UASS)

 Promote advice for researchers conducting UASS drift studies

9

# **UAPASTF Best Practices Document Process**

- UAPASTF BMP technical committee formed March 2022
- Reviewed related available Stewardship, SOP and BP documents for UAV and manned aircraft: Crop Life (CLI, CLA); Int. Org. (FAO), Governments (India, Japan); Associations (NASDARF); Pesticide industry (FMC, Valent Biosciences); Drone spraying servicer (Rantizo)
- Delivered first draft November 2022 and sent for review by multiple internal and external experts (NDA signed with TF)
- Comments incorporated, "Final Draft" sent broadly to additional international experts and organizations for review – March 2023
- Today's BMP workshop to get input from OECD workshop attendants

UAPASTF Member Company	BMP Tech Team Rep
BASF	Mark Oostlander
Bayer	Sarah Hovinga
Corteva	Rajeev Sinha
FMC	Hector Portillo
	Ted Lang
	Roberto Barbosa
Nufarm	Tyler Gullen
Syngenta	Neill Newton
	Pam Livingston
	Becca Haynie
Valent	Banugopan Kesavaraju
Rantizo	Matt Beckwith

### **Unmanned Aerial Spray System (UASS) Best Practices Components**



**Best Practices for Safe and Effective Application of Agrochemicals Using Unmanned Aerial Spray Systems (UASS)** 

Strong of			
PEST AND CROP	PRODUCT AND TANK MIX	ENVIRONMENTAL CONDITIONS	OPERATOR/CERTIFICATION AND EQUIPMENT/SPRAY SYSTEM
<ul> <li>Assess if use of UASS is the appropriate method for the crop/pest targeted; use labeled</li> <li>Pest/disease/weed ID, threshold, timing</li> <li>Water volume/Spray coverage adequate for crop stage, pest location</li> </ul>	<ul> <li>Product: attributes i,e., systemic Vs contact, use rate, rainfastness</li> <li>Clean tank, lines, and booms</li> <li>Tank mix: water quality and temp, adjuvants, buffers, compatibility, order of addition, suspensibility etc.</li> <li>Label requirements</li> </ul>	<ul> <li>Preferred conditions: wind, temperature, relative humidity</li> <li>Marginal conditions: low or high winds, Surface temperature inversions (thermal inversion), rain</li> <li>Label requirements to avoid operator exposure and sensitive areas: water bodies, pollinators etc.</li> </ul>	<ul> <li>Certifications to Apply Pesticides with UAVs</li> <li>Select equipment UAV, nozzle type, flow rate capacity for required water volume</li> <li>Calibration and deposition</li> <li>Preapplication crew briefing, field survey, flight path</li> <li>Monitor spray quality</li> </ul>

#### -FMC **Considerations to Deliver Product to the Target Using UAV**





**Rice Stem Borer** 



**Almond- Navel Orange Worm** Spray must reach the almond hull split suture



# The High Number of Drone/UASS Platforms Makes it Difficult to Make Broad Recommendations



Single Rotor- Gasoline/Battery





Multi (4) Rotor & in-line CDA nozzle





Fixed Wing – Battery/No Rotors



Multi (8) Rotor & in-line hydraulic nozzle



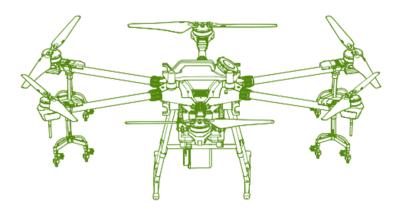
Multi (6) Rotor – Boom config.

# Drone Technology for Pesticide Application: *Aircraft vs Spray System*

### **UAV system and flight control**

### Motors & Propulsion System

- Propeller
- Motors
- Electronic Speed Controller



### Power, Sensing, Control System

- Navigation Sensor
- Battery
- Flight Controller

#### **Liquid Delivery System**

Spray tank	<ul> <li>Small payload capacity (10- 40 L)</li> <li>No tank agitation/ bypass</li> </ul>	
Delivery pump	<ul> <li>Diaphragm or peristaltic pumps</li> <li>Limited by mass flow rate, low capacity, impacts volume output/droplet size</li> </ul>	
Nozzle & boom	<ul> <li>Various configurations, booms or under rotor</li> <li>Some UASS not flexible on type of nozzle that can be used</li> </ul>	









# Spray Equipment Calibration Is Critical – Not well Understood for UASS

Calibration ensures:

- Delivery of <u>accurate amount of product</u> as label rate
- Uniform distribution of active ingredients over the field or to the targets
- Three major factors influence sprayer calibration:
  - Ground speed, i.e., flight speed (km/h, miles/h)
  - Swath width (meters or feet) Impacted by flight height, nozzle/boom configuration
  - Flow rate (L/min or g/min)



### **Best Practices Guidance Document Next Steps**

- Draft shared with UAPASTF collaborators for review, including members present at this workshop
- Expert feedback, Day 2 of CRD-HSE and OECD CRP sponsored workshop on the application of pesticides by drone, May 23-24, 2023, York, UK
- Incorporate workshop feedback and finalize BMP document
- Decide who/how document will be updated

# THANK YOU!

